ASEN 6008 Interplanetary Mission Design

Lecture s: Monday 6:00 -

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- c. The N-body problem
- d. Perturbations
- e. Patched conics
- f. Reference frames
- g. Sphere of Influence
- h. Hohmann transfers
- II. Lambert's Problem
 - a. Lambert's general theorem
 - b. Type I vs Type 2 orbits
 - c. Discussion of Geometry of Lambert's problem
 - d. Universal Variables Algorithm
 - e. Revisit f and g functions
 - f. TOF equations for elliptical, parabolic, and hyperbolic transfers
 - g. Multi-Revolution solutions (Type 3, Type 4, etc)
 - h. Algorithm for multi-rev solutions
- III. Ephemeris
 - a. Meeus Coefficients
 - b. Discussion of JPL Ephemerides
- IV. Pork Chop Plots
 - a. Construction and Analysis
- V. Gravity Assists
 - a. History
 - b. Vector Diagrams
 - c. Leading vs Trailing
 - d. Geometry
 - e. Computation of parameters (periapsis radius, turn angles, etc)
- VI. B-

- i. Deterministic vs Stochastic
- g. Examples of optimization algorithms
- X. Tisserand Plots
- XI. Three Body Problem
 - a. History
 - b. Simplified forms (Restricted, Elliptical Restricted, Circular Restricted)
- XII. Circular Restricted Three Body Problem
 - a. Geometry of nondimensional, rotating frame
 - b. Derivation of Equations of Motion
 - c. Transformation from synodic to inertial frame
 - d. Libration Points
- XIII. State Transition Matrix
 - a. Motivation
 - b. Derivation for CRTBP
- XIV. Libration Point Orbits
 - a. History in Mission Design
 - b. Types of orbits (Halo, Lissajous, etc)
 - c. Construction of LPOs using Single Shooting Algorithm
 - d. Stability
- XV. Invariant Manifolds
 - a. Definition
 - b. Stable/Unstable Eigenvalues and vectors
 - c. Computing Invariant Manifolds (general discussion)
 - d. Applications to Mission design
- XVI. Differential Correction

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See the campus policy regarding religious observances for full details.

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