

Wavefront sets of solutions to linearised inverse scattering problems

Weita Chang[†], Philip Carrion[‡] and Gregory Beylkin[§]

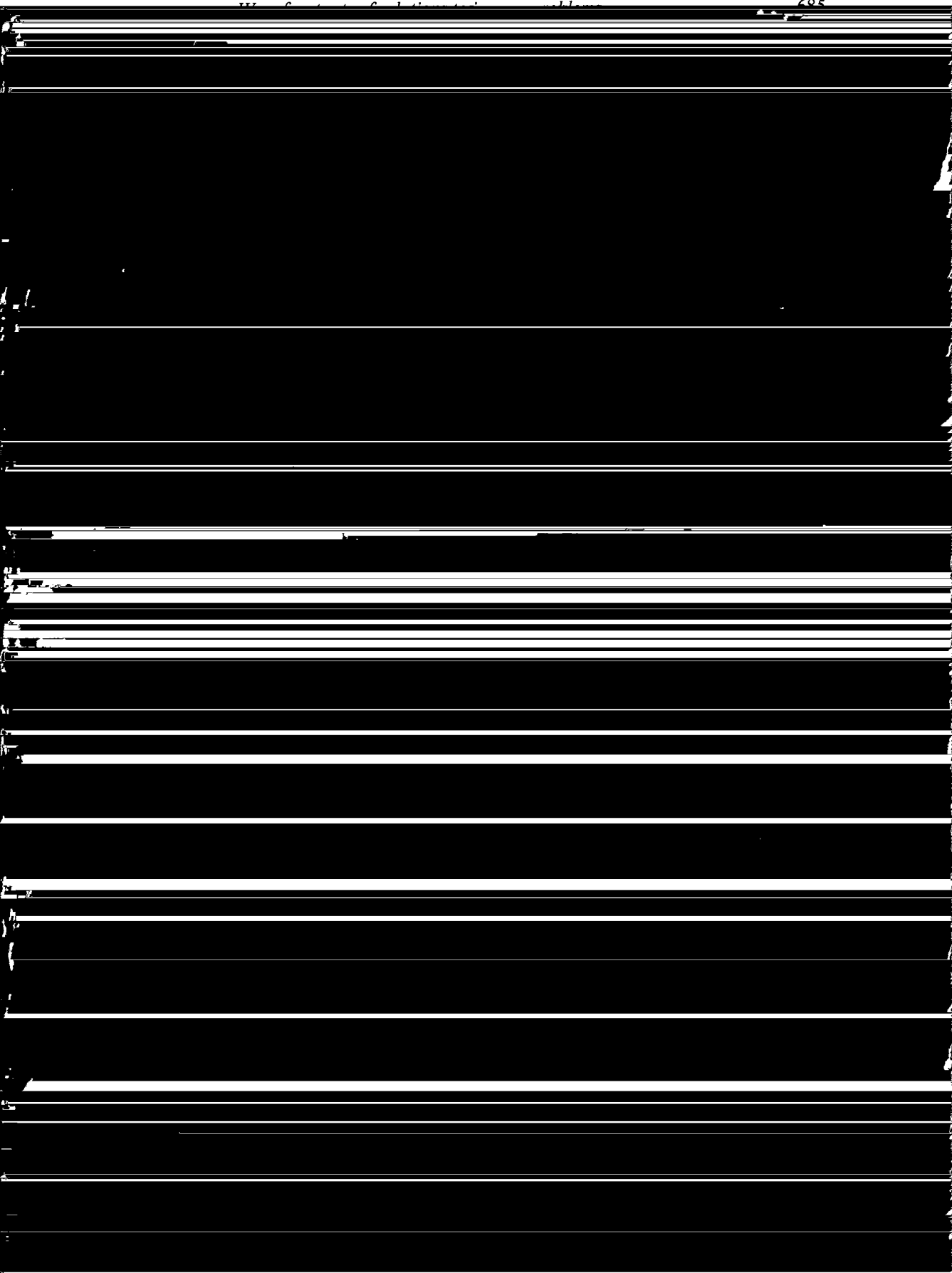
[†] Naval Underwater Systems Center, Code 3315, New London, CT 06320, USA

[‡] Georgia Institute of Technology, School of Geophysical Sciences, Atlanta, GA 30332

In [10] precise answers to these questions are given using the notion of a generalised Radon transform [23]. In particular the answer is affirmative to the first question.

The purpose of this short paper is to reformulate the results of [10] in terms of wavefront sets. This provides a natural framework for formulating the inverse problem in general as one of determination of wavefront sets of unknown parameters of PDEs, which is a meaningful question to ask from the point of view of applications.

Such a formulation is also meaningful from the pure mathematical point of view. In other words, the wavefront set of a function seems to be a natural notion to use in problems of reconstructing discontinuities. Recall that the concept of the wavefront set is



satisfying the eikonal equation

$$|\nabla_x \varphi(x, \xi)|^2 = n_0^2(x) \quad (3.2)$$

for $x \in X$, and $\xi \in \partial X$, such that

$$\varphi(x, \xi) \rightarrow 0 \quad \text{as } x \rightarrow \xi. \quad (3.3)$$

We also assume that $\varphi(x, \xi)$ satisfies conditions (2.1), (2.2). For example if $n_0(x)$ is constant, say $n_0(x) = 1$ — the constant background model — we have

states that the locations of discontinuities together with their infinitesimal directions can be (at least partially) recovered. In fact the migration schemes described in [13–21] all have various choices for B , motivated in simple cases (e.g. a constant background) by some kind

Appendix

Here we state the basic facts about pseudodifferential operators. Let X be an open set of R^n .

Definition (cf [7] vol. 1, p 13). The space of symbols of degree m , denoted by

$$S^m(X \times X \times R^n \setminus \{0\})$$

consists of all complex-valued functions

$$C(x, y, \theta) \in C^\infty(X \times X \times R^n \setminus \{0\})$$

where

$$p = \nabla_x \Phi(x, x, \theta).$$

Since the determinant factor is non-zero and positive homogeneous degree 0 in p , we conclude that T is elliptic at (x_0, p_0) if

$$|C(x, x, \theta)| \geq d|\theta|^m$$

for all (x, θ) in some conic neighbourhood of (x_0, θ_0) where

$$p_0 = \nabla_x \Phi(x_0, x_0, \theta_0)$$

and d is some positive constant. From this we get the following corollary.

Corollary A.2 Let $Tf = g$ be as in proposition A.1, then

- [15] French W S 1974 Two-dimensional and three-dimensional migration of model experiment reflection profiles *Geophys.* **39** 265–77
- [16] Schneider W A 1978 Integral formulation for migration in two and three dimensions *Geophys.* **43** 49–76
- [17] Stolt R M 1978 Migration by Fourier transform *Geophys.* **43** 23–48
- [18] Cohen J K and Bleistein N 1979 Velocity inversion procedure for acoustic waves *Geophys.* **44** 1077–85
- [19] Berkhout A J 1980 *Seismic Migration* (Amsterdam: Elsevier)
- [20] Gelchinsky B 1983 *Ray Asymptotic Migration (Basic concepts), Extended Abstracts of 53rd SEG Meeting, Society of Exploration Geophysics, Las Vegas (SEG)* pp 385–7
- [21] Carter J A and Fraser L N 1984 Accommodating lateral velocity changes in Kirchhoff migration by means of Fermat's principle *Geophys.* **49** 46–53
- [22] Stolt R H and Weglein A B 1985 Migration and inversion of seismic data *Geophys.* **50** 2458–72
- [23] Beylkin G 1984 The inversion problem and applications of the generalized Radon transform *Commun. Pure Appl. Math.* **37** 579–99